An Introduction to Jack Symmetric Functions

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November 2023

Abstract

Jack symmetric functions are a one-parameter generalization of Schur symmetric functions. In the twenty minutes provided, I'll define Jack symmetric functions and talk about a particular basis for them. Then I'll describe why hook lengths are important to evaluating the scalar product on these objects.

Defining Jack Symmetric Functions

- Recall:
 - $-m_{\lambda}$ are monomial symmetric functions
 - $-p_{\lambda}$ are the power sum symmetric functions.
- Jack functions are a one parameter generalization of the Schur functions.
- Notation: We write $J_{\lambda}(x_1, x_2, \ldots; \alpha)$ for the Jack function corresponding to the partition λ .
- They are characterized by satisfying the following three conditions.
 - Orthogonality: $\langle J_{\lambda}, J_{\mu} \rangle = 0$ when $\lambda \neq \mu$ where the scalar product is defined by $\langle p_{\lambda}, p_{\mu} \rangle = \delta_{\lambda\mu} z_{\lambda} \alpha^{\ell(\lambda)}$.
 - Triangularity: Select coefficients $v_{\lambda\mu}(\alpha)$ so that

$$J_{\lambda} = \sum_{\mu} v_{\lambda\mu}(\alpha) m_{\mu}.$$

Then $v_{\lambda\mu}(\alpha) = 0$ unless $\mu \leq \lambda$ (dominance order). In other words, the c.o.b. matrix from the *m* basis to the *J* basis is upper triangular. *Uh, from what to what?*

- Normalization: If $|\lambda| = n$, then the coefficient $v_{\lambda 1^n}$ of $x_1 x_2 x_3 \cdots x_n$ of J_n is n!.
- I won't prove this. (Stanley doesn't either.)
- Here are a couple down-to-earth examples.

$$J_1(x_1, x_2, \dots; \alpha) = x_1 + x_2 + x_3 + \dots$$
$$J_{1^n} = n! m_{1^n} = n! e_n$$

- Question: So how do we specialize to the Schur symmetric functions?
- Identify λ with its Young diagram.
- **Def'n:** The hook length of the box $\Box \in \lambda$ is $h(\Box) = a(\Box) + \ell(\Box) + 1$.

• Def'n: We write

$$H_{\lambda} = \prod_{\Box \in \lambda} h(\Box)$$

for the product of all the hook lengths of λ .

• **Example:** Let $\lambda = (3, 3, 2)$.



- The hook length of the red box is 3.

- Each box contains its hook length in the tableau below.

| 5 | 4 | 2 |
|---|---|---|
| 4 | 3 | 1 |
| 2 | 1 | |

- So $H_{\lambda} = 5 \cdot 4 \cdot 2 \cdot 4 \cdot 3 \cdot 1 \cdot 2 \cdot 1 = 960.$

- Answer: $J_{\lambda}(x_1, x_2, x_3, ...; 1) = H_{\lambda} s_{\lambda}(x_1, x_2, x_3, ...).$
- Proof (sketch): Stanley chapter 7 explains how s_{λ} satisfies the first two conditions. What is the coefficient of $x_1 x_2 \cdots x_n$ in s_{λ} ? It's $f^{\lambda} = \frac{n!}{H_{\lambda}}$.
- Now let's talk about how to evaluate nontrivial scalar products. We'll need to define an alpha generalization of hook length.
- **Def'n:** We say $j_{\lambda} = \langle J_{\lambda}, J_{\lambda} \rangle$.
- **Def'n:** For a partition λ define

$$h_{\lambda}^{*}(\Box) = \ell(\Box) + \alpha(a(\Box) + 1)$$
$$h_{*}^{\lambda}(\Box) = 1 + \ell(\Box) + \alpha \cdot a(\Box).$$

In other words, arm boxes contribute an α to the hook length and leg boxes contribute a 1 to the hook length. The pivot box contribution is the difference between the upper and lower hook lengths. In the upper hook length the pivot gets an α and in the lower hook length it gets a 1.

- Note that this is the normal hook length when $\alpha = 1$.
- Prop: We have

$$j_{\lambda} = \prod_{\Box \in \lambda} h_{\lambda}^*(\Box) h_*^{\lambda}(\Box).$$

- I won't prove this today.
- **Example:** Let $\mu = (3, 2)$. Then j_{μ} is the product of all of the expressions in the boxes below.

| $\frac{3\alpha + 1}{2\alpha + 2}$ | $\frac{2\alpha + 1}{\alpha + 2}$ | lpha 1 |
|-----------------------------------|----------------------------------|--------|
| $\frac{2\alpha}{\alpha+1}$ | lpha 1 | |